

# Elastic-wave AVO methods

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### Summary

For more than 3 decades, industry has known that shear seismic waves (S-waves) contain different information about rock properties than do standard compressional seismic waves (P-waves). Efforts to record PS converted-waves, even on the seabed, have attracted industry attention with increasing success. Separate efforts to analyse conventional pre-stack P-wave gathers for the S-wave information contained or “missing” within them, have had more success and popularity as a function of significantly lower recording cost and relatively simpler analysis. These methods termed P-wave AVO are a logical and quantifiable petrophysical extension into pre-stack seismic data from the confusing and simplistic interpretation of stacked amplitudes. Since the mid 90’s new AVO inversion methods have been gradually succeeding in the exploration and development of gas pools within both clastic and carbonate plays. This paper compares various P-wave and PS converted wave AVO methods to estimate normal incidence P and S reflectivity ( $R_p$  and  $R_s$ ) and extends the AVO equations for the potential to combine P-wave and PS converted wave AVO for a more robust method to extract elastic parameters such as Lamé parameters  $\lambda$  and  $\mu$ , or  $\Lambda\rho$  and  $\mu\rho$ . These various methods will be applied to surface and walkaway VSP “AVO gather” data examples and verified to sonic and dipole log measurements. The presentation will also attempt to understand the value that this additional shear information has in exploration seismic applications.

### Angle dependent reflectivity equations and approximations for AVO seismic or VSP analysis.

**P-wave;** A common starting point for AVO analysis is the linearized 3 term approximation to the Knott-Zoeppritz equations given by Aki and Richards (1980) shown below (equations 1, 7 and 8). These form the starting point for further 2 term approximations as the number of unknowns should not exceed the measurable CMP gather quantities (intercept and gradient) to ensure robust unambiguous parameter estimates, especially in the presence of noise (Cambois 2000). The basic linearized Aki and Richards assumptions are small fractional velocity and density changes with 2nd order terms ignored and  $\theta_p < 10$  degrees of critical.

$$R_{pp}(\theta) = \frac{1}{2} \left( \frac{\Delta V_p}{V_p} + \frac{\Delta \rho}{\rho} \right) - 2 \frac{V_s^2}{V_p^2} \sin^2 \theta_p \left( 2 \frac{\Delta V_s}{V_s} + \frac{\Delta \rho}{\rho} \right) + \frac{1}{2} \tan^2 \theta_p \frac{\Delta V_p}{V_p} \quad (1)$$

where:  $V_p$ ,  $V_s$  velocities,  $\rho$  density, are averaged across an interface and angle  $\theta_p$  (or just  $\theta$ ) is the average of incident and transmitted P-wave.  $\Delta V_p/V_p$ ,  $\Delta V_s/V_s$ ,  $\Delta \rho/\rho$  are fractional changes in  $V_p$ ,  $V_s$  and  $\rho$  across an interface and are equivalent to  $\Delta \ln V_p$ ,  $\Delta \ln V_s$  and  $\Delta \ln \rho$ . The common industry method considered here extracts  $R_p(0)$  and  $R_s(0)$  “seismic traces” through “weighted stacking” of CMP gather data (Gidlow et. al.1992, Fatti et. al.1994) which can be inverted into  $\lambda\rho$  and  $\mu\rho$ . Starting from the Aki & Richards equation above with some algebraic manipulation gives;

$$R_{pp}(\theta) = (1 + \tan^2 \theta) \frac{\Delta I_p}{2I_p} - 8 \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta \frac{\Delta I_s}{2I_s} - \left( \frac{1}{2} \tan^2 \theta - 2 \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta \right) \frac{\Delta \rho}{\rho} \quad (2)$$

$$\text{with } \frac{\Delta I_p}{2I_p} = R_{pp}(0) = \frac{1}{2} \left( \frac{\Delta V_p}{V_p} + \frac{\Delta \rho}{\rho} \right) \quad \frac{\Delta I_s}{2I_s} = R_{ss}(0) = \frac{1}{2} \left( \frac{\Delta V_s}{V_s} + \frac{\Delta \rho}{\rho} \right)$$

Equation (2) the “Geogain Equation” from Gidlow et. al. 1992, is solved in a least squares sense to extract  $R_p$  and  $R_s$  by assuming the 3rd term cancels for small density contrasts ( $\Delta \rho/\rho$ ), as well as for small angles i.e.  $\tan^2 \theta_p = \sin^2 \theta_p$ , and  $(V_s/V_p) = 1/2$ . If the density contrast is not small then this third “error” term can be significant at large angles and more importantly inconsistent for varying rock properties by being dependent on both angle and  $V_p/V_s$  ratio. For  $V_p/V_s$  ratios  $< 2$  the error between this 2 term equation and the exact Aki & Richards 3 term curve is small and evenly distributed, but still angle dependent. However for ratios  $> 2.5$  or 3, this error increases with increasing angle and because the error term is strongly dependent on both angle and  $V_p/V_s$  ratio this restricts the useable range of angles.

In practice, however, this equation is very useful and can be used to fairly large angles as  $\Delta \rho/\rho$  has the smallest variation compared to  $\Delta V_p/V_p$  and  $\Delta V_s/V_s$ , seen in Gardner’s (1974) relationship as  $\Delta \rho/\rho \approx (\Delta V_p/V_p)/4$ . If the angle range is restricted to a commonly quoted  $30^\circ$  due to the ignored error term, then the catch-22 problem is that the same large angle restriction reduces the separability of sin and tan curves involved in the remaining first two terms of equation (2). If this angle restriction can be reduced then more robust and independent estimates of  $\Delta I_p/I_p$  and  $\Delta I_s/I_s$  are possible in theory. However a different approximation with no angle dependent error can be obtained by substituting the following relationships into the original Aki & Richards equation (1) above;

$$\frac{\Delta I_s}{2I_s} = \frac{1}{4} \left( \frac{\Delta \mu}{\mu} + \frac{\Delta \rho}{\rho} \right), \quad \frac{\Delta V_p}{2V_p} = \frac{1}{4} \left( \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} - \frac{\Delta \rho}{\rho} \right) \quad \text{and} \quad \frac{\Delta V_s}{2V_s} = \frac{1}{4} \left( \frac{\Delta \mu}{\mu} - \frac{\Delta \rho}{\rho} \right) \quad (3)$$

$$\Rightarrow R_{pp}(\theta) = \frac{\Delta \rho}{2\rho} + (1 + \tan^2 \theta) \frac{\Delta V_p}{2V_p} - 4 \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta \frac{\Delta \mu}{2\mu} \quad (4)$$

Now the approximation in this equation (4) (Goodway, 1997), is to drop the small zero offset term  $\Delta \rho/2\rho$  (again from Gardner’s relationship  $\Delta \rho/2\rho \approx (\Delta V_p/V_p)/8$ ). Note that this error is independent of angle unlike the Gidlow et. al. 2 term approximations and hence allows a more accurate fit to the exact Aki & Richards AVO curve at large angles, but has a “bulk”  $\Delta \rho/2\rho$  scalar shift at all angles. These 2 term approximations are compared to the Aki and Richards 3 term equation as graphed against incident angle in figure 1 below. Yet further interesting reformulations of the original Aki & Richards AVO equation can be obtained in terms of linear  $\cos 2\theta$  only and Lamé moduli, density terms using the relationships in equation (3) above, as;

$$R(\theta) = \frac{1}{2(1 + \cos 2\theta)} \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} - (1 - \cos 2\theta) \left( \frac{V_s}{V_p} \right)^2 \frac{\Delta \mu}{\mu} + \frac{\cos 2\theta}{2(1 + \cos 2\theta)} \frac{\Delta \rho}{\rho} \quad (5)$$

Note in equation (5) there is no density influence on  $R(\theta)$  at  $45^\circ$  i.e.  $R(\theta)$  is just a function of moduli as a ratio that is almost  $\Delta(Vp/Vs)^2/(Vp/Vs)^2$ . This concurs with Hilterman's work on far offset reflectivity (course notes on AVO accompanying the SEG DISC 2001). Finally a useful quadratic equation in terms of  $\cos 2\theta$ :

$$R(\theta)2(1 + \cos 2\theta) = \frac{\Delta\lambda}{(\lambda + 2\mu)} + \cos 2\theta \left( \frac{\Delta\rho}{\rho} + 2 \cos 2\theta \frac{\Delta\mu}{(\lambda + 2\mu)} \right) \quad (6)$$

shows a similar though more interesting insight, to equation (5) above. The insight here is that at  $\theta = 45^\circ$  the reflectivity  $R(45)$  is just a scaled version of the change in the basic fluid sensitive indicator  $\Delta\lambda$  as;

$$2R(45) = \frac{\Delta\lambda}{(\lambda + 2\mu)} \quad \text{where } \lambda + 2\mu = I_p \cdot V_p \text{ (product of averaged P impedance and interval velocity)}$$

**PS and S-wave;** The Aki and Richards approximations to Zoeppritz equations for  $R_{ps}(\theta)$  and  $R_{ss}(\theta)$  are shown below with the same assumptions as the P-wave equations. These form the starting point for yet further approximations and combinations of PS and SS reflectivity equations used to extract  $R_s(0)$  that will be considered.

$$R_{ps}(\theta) = \frac{-\rho V_p}{2 \cos \theta_s} \left[ \left( 1 - 2V_s^2 \mathbf{p}^2 + 2V_s^2 \frac{\cos \theta_p \cos \theta_s}{V_p V_s} \right) \frac{\Delta\rho}{\rho} - \left( 4V_s^2 \mathbf{p}^2 - 4V_s^2 \frac{\cos \theta_p \cos \theta_s}{V_p V_s} \right) \frac{\Delta V_s}{V_s} \right] \quad (7)$$

$$R_{ss}(\theta) = -\frac{1}{2} (1 - 4V_s^2 \mathbf{p}^2) \frac{\Delta\rho}{\rho} - \left( \frac{1}{2 \cos^2 \theta_s} - 4V_s^2 \mathbf{p}^2 \right) \frac{\Delta V_s}{V_s} \quad (8)$$

where  $\mathbf{p}$  is the constant ray parameter  $\sin \theta_s/V_s$  or  $\sin \theta_p/V_p$ , approximated to the average ray parameter.

Substituting equation (8) into equation (7) gives;

$$R_{ps}(\theta) = \frac{-\rho V_p}{2 \cos \theta_s} \left[ \left( 2V_s \cos \theta_s \frac{\cos \theta_p}{V_p} \right) \left( \frac{\Delta\rho}{\rho} + \frac{2\Delta V_s}{V_s} \right) - R_{ss} + \frac{\Delta\rho}{2\rho} - \frac{1}{2 \cos^2 \theta_s} \frac{\Delta V_s}{V_s} \right] \quad (9)$$

Next by assuming  $\cos \theta_s = 1$ ,  $\cos^2 \theta_s = 1$ ,  $\sin \theta_s = 0$  gives;

$$R_{ps}(\theta) \approx -\rho V_s \left[ \left( \frac{2\Delta V_s}{V_s} + \frac{\Delta\rho}{\rho} \right) \cos \theta_p + \frac{V_p \Delta\rho}{2V_s \rho} \right] \quad (10)$$

This approximation for  $R_{ps}(\theta)$  (equation 10) can be seen to be the same as the Stewart et. al. (1997) approximation;

$$R_{ps}(\theta) \approx 4(V_s/V_p) \sin \theta_p R_{ss}(0), \text{ but without the } \cos \theta_p = 1 \text{ assumption.}$$

Rearranging the Stewart et. al. approximation;

$$\Rightarrow R_{ss}(0) \approx (V_p/4V_s) \csc \theta_p R_{ps}(\theta) \quad (11)$$

Similarly equation (10) can be rearranged to give an  $R_{ss}(0)$  estimate by scaling  $R_{ps}(\theta)$  by assuming  $[(V_p/2V_s) - \cos \theta_p] \Delta\rho/\rho$  is zero for small  $\Delta\rho/\rho$  and  $\theta_p$  as well as  $V_p/V_s \approx 2$ ;

$$\Rightarrow R_{ss}(0) \approx R_{ps}(\theta) / \sin \theta_s 4 \cos \theta_p = (V_p/2V_s) \csc 2\theta_p R_{ps}(\theta) \quad (12)$$

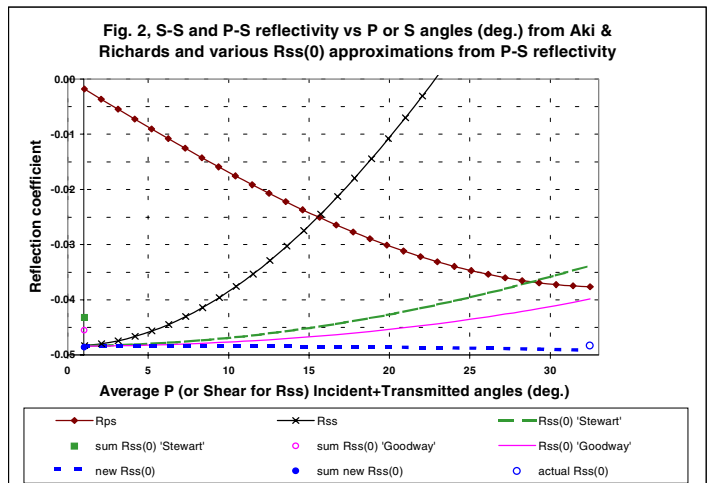
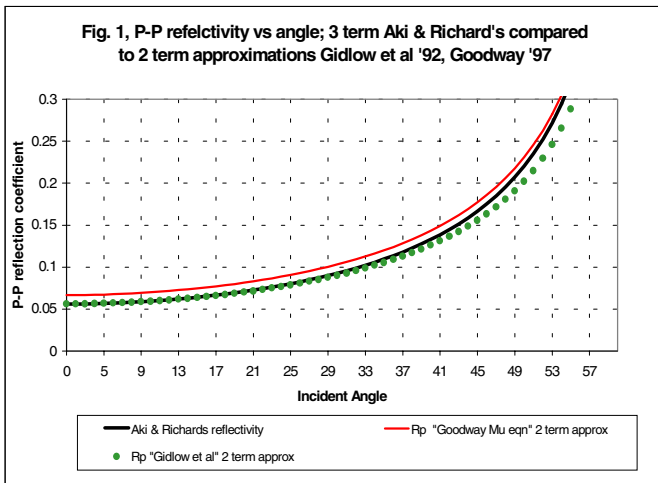
A further improvement for an  $R_s(0)$  estimate is shown below (Larsen et. al. 1999) by substituting the relationships in equation 3, into the  $R_{ps}$  AVO Aki & Richards equation (7) given above;

$$R_{ps}(\theta) = -\tan \theta_s \left[ \frac{V_p}{V_s} \left( \frac{1}{2} + \sin^2 \theta_s \right) - \cos \theta_s \cos \theta_p \right] \frac{\Delta\rho}{\rho} - \left( \frac{V_p}{V_s} \tan \theta_s \sin^2 \theta_s - \sin \theta_s \cos \theta_p \right) 4R_{ss}(0)$$

$$\text{dropping the } \frac{\Delta\rho}{\rho} \text{ term assuming small density contrasts } \Rightarrow R_{ps}(\theta) \approx - \left( \frac{V_p}{V_s} \tan \theta_s \sin^2 \theta_s - \sin \theta_s \cos \theta_p \right) 4R_{ss}(0)$$

$$\Rightarrow R_{ss}(0) \approx \frac{-R_{ps}(\theta)}{4 \sin \theta_s (\tan \theta_s \sin \theta_p - \cos \theta_p)} \quad (13)$$

These 3 approximations, the Stewart equation 11 (labeled  $R_{ss}(0)$ 'Stewart') and equation 12 (labeled  $R_{ss}(0)$ 'Goodway') as well as the new equation 13 (labeled 'new  $R_{ss}(0)$ '), are compared below in figure 2, using the same model layer parameters used by Stewart et. al. (1997) for predicting  $R_{ss}(0)$  by averaged summation or stacking. In conclusion the 'Goodway' equation (12) is a slightly better approximation than the 'Stewart' equation (11), while the new equation (13) has the best estimate of  $R_{ss}(0)$



### Combined PP and PS AVO inversion to obtain accurate estimates of Lamé moduli and density reflectivity.

The following combined P-wave and converted wave inversion method follows the various weighted stacking approaches of Smith et. al. 1987, Stewart 1991, Gidlow et. al. 1992 and Larsen et. al. 1999, to invert the Aki and Richards (1980) approximations to Zoeppritz equations for Rpp( $\theta$ ) alone or joint Rpp( $\theta$ ) and Rps( $\theta$ ), so as to obtain estimates of P- and S-wave reflectivity i.e. Rp(0) and Rs(0). However by contrast to these previously published methods, the derivations that follow are exact and do not rely on dropping terms in fractional density changes or empirical (Gardner et. al. 1974) relationships between density and velocity (Vp) or impedance (Ip). First rewriting the Aki and Richards Rpp (equation 1) in terms of Lamé parameters using the substitutions in equation (3) above;

$$R_{pp}(\theta) = \frac{1}{4}(1 + \tan^2 \theta_p) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} - 2 \sin^2 \theta_p \left( \frac{V_s}{V_p} \right)^2 \frac{\Delta\mu}{\mu} + \frac{1}{4}(1 - \tan^2 \theta_p) \frac{\Delta\rho}{\rho} \quad (14)$$

Next rewriting the Rps equation 7, in Lamé parameter terms using the  $\Delta V_s/V_s$  substitution equation (3) above;

$$R_{ps}(\theta) = -\frac{V_p \tan \theta_s}{V_s} \frac{\Delta\rho}{2\rho} + \frac{V_s}{V_p} (\sin^2 \theta_p \tan \theta_s - \sin \theta_p \cos \theta_p) \frac{\Delta\mu}{\mu} \quad (15)$$

From this Rps result either the density reflectivity  $\Delta\rho/\rho$  or the shear or rigidity reflectivity  $\Delta\mu/\mu$  terms can be replaced in the Lamé formulated Rpp equation (14).

#### 1) Replacing density reflectivity $\Delta\rho/\rho$ .

Rearranging the Rps equation (15);

$$\Rightarrow \frac{\Delta\rho}{\rho} = 2 \left( \frac{V_s}{V_p} \right)^2 \left( \sin^2 \theta_p - \frac{\sin \theta_p \cos \theta_p}{\tan \theta_s} \right) \frac{\Delta\mu}{\mu} - 2 \frac{V_s}{V_p} \frac{R_{ps}(\theta)}{\tan \theta_s}$$

replacing  $\frac{\Delta\rho}{\rho}$  in Rpp equation (14)

$$\Rightarrow R_{pp}(\theta) + \frac{1}{2} \frac{V_s}{V_p} \frac{(1 - \tan^2 \theta_p)}{\tan \theta_s} R_{ps}(\theta) = \frac{1}{4}(1 + \tan^2 \theta_p) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} - \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta_p \left[ \left( \frac{\sin \theta_p}{2} (3 + \tan^2 \theta_p) + \frac{\cos \theta_p}{2 \tan \theta_s} (1 - \tan^2 \theta_p) \right) \right] \frac{\Delta\mu}{\mu} \quad (16)$$

This last equation (16) is an exact relationship combining Rpp( $\theta$ ) with an angle and  $V_s/V_p$  scaled version of Rps( $\theta$ ) expressed in terms of only the two fractional changes of moduli or reflectivity i.e. P-modulus  $\Delta(\lambda+2\mu)/(\lambda+2\mu)$  and shear modulus  $\Delta\mu/\mu$ .

#### 2) Replacing rigidity reflectivity $\Delta\mu/\mu$ .

Rearranging the Rps equation (15);

$$\Rightarrow \frac{\Delta\mu}{\mu} = \frac{V_p}{V_s} \left[ \frac{\left( R_{ps}(\theta) + \frac{V_p \tan \theta_s}{V_s} \frac{\Delta\rho}{2\rho} \right)}{(\sin^2 \theta_p \tan \theta_s - \sin \theta_p \cos \theta_p)} \right] \Rightarrow 2 \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta_p \frac{\Delta\mu}{\mu} = 2 \frac{V_s}{V_p} \left( R_{ps}(\theta) + \frac{V_p \tan \theta_s}{V_s} \frac{\Delta\rho}{2\rho} \right) \frac{\sin^2 \theta_p}{(\sin^2 \theta_p \tan \theta_s - \sin \theta_p \cos \theta_p)}$$

$$\Rightarrow -2 \left( \frac{V_s}{V_p} \right)^2 \sin^2 \theta_p \frac{\Delta\mu}{\mu} = 2 \frac{\sin \theta_s \cos \theta_s}{\cos(\theta_p + \theta_s)} R_{ps}(\theta) + \frac{\sin \theta_p \sin \theta_s}{\cos(\theta_p + \theta_s)} \frac{\Delta\rho}{\rho} \quad (17) \quad \text{next replacing } \frac{\Delta\mu}{\mu} \text{ in Rpp equation (14) using equation (17)}$$

$$\Rightarrow R_{pp}(\theta) = \frac{1}{4}(1 + \tan^2 \theta_p) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} + \left[ \frac{1}{4}(1 - \tan^2 \theta_p) + \frac{\sin \theta_p \sin \theta_s}{\cos(\theta_p + \theta_s)} \right] \frac{\Delta\rho}{\rho} + 2 \frac{\sin \theta_s \cos \theta_s}{\cos(\theta_p + \theta_s)} R_{ps}(\theta)$$

$$\Rightarrow R_{pp}(\theta) - 2 \frac{\sin \theta_s \cos \theta_s}{\cos(\theta_p + \theta_s)} R_{ps}(\theta) = \frac{1}{4}(1 + \tan^2 \theta_p) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} + \left[ \frac{1}{4}(1 - \tan^2 \theta_p) + \frac{\sin \theta_p \sin \theta_s}{\cos(\theta_p + \theta_s)} \right] \frac{\Delta\rho}{\rho} \quad (18)$$

In a similar, though simpler result, this last equation (18) is an exact relationship combining Rpp( $\theta$ ) with an angle scaled version of Rps( $\theta$ ) expressed in terms of P-modulus  $\Delta(\lambda+2\mu)/(\lambda+2\mu)$  and density  $\Delta\rho/\rho$  reflectivity. Both equations (16) and (18) can be expressed in linearly weighted forms;

$$R_{pp}(\theta) + m(\theta)R_{ps}(\theta) = A(\theta) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} + B(\theta) \frac{\Delta\mu}{\mu} \quad (19) \quad \text{and} \quad R_{pp}(\theta) + n(\theta)R_{ps}(\theta) = C(\theta) \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} + D(\theta) \frac{\Delta\rho}{\rho} \quad (20)$$

where m and n are angle dependent scalars and coefficients A, B, C and D are angle dependent weights.

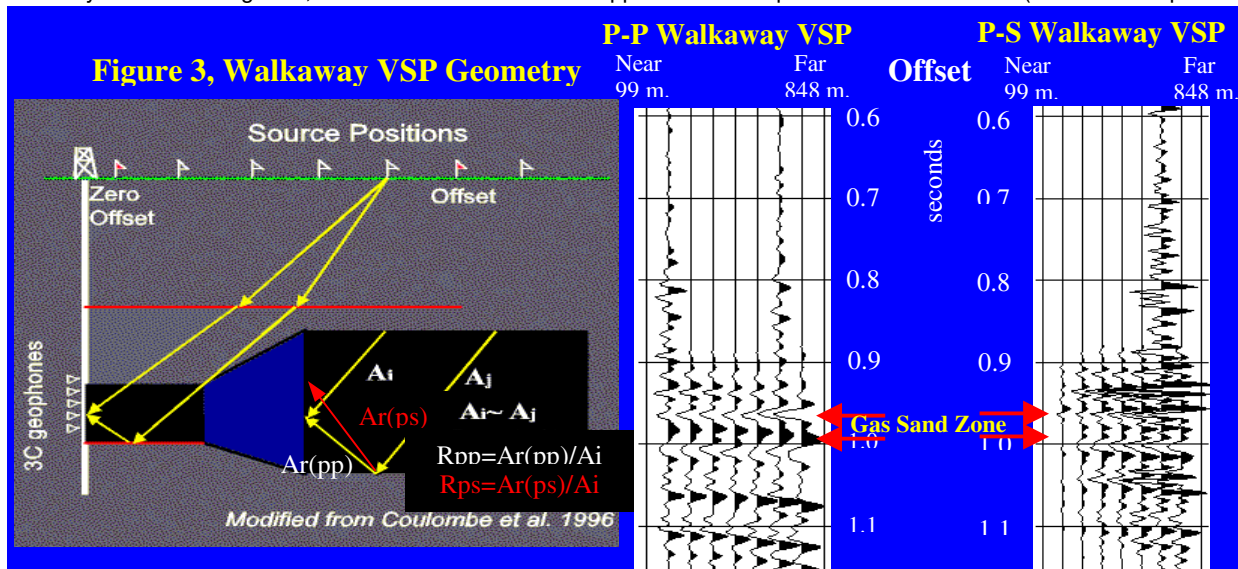
Either equation (19) or (20) can be used in standard least-squares AVO model to data  $r(\theta)$  error minimisation to give a pair of simultaneous equations that can be inverted for elastic parameter estimates  $\Delta(\lambda+2\mu)/(\lambda+2\mu)$ ,  $\Delta\mu/\mu$  and  $\Delta\rho/\rho$  as shown by the matrices below;

$$\begin{bmatrix} \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} \\ \frac{\Delta\mu}{\mu} \end{bmatrix} = \begin{bmatrix} \sum_{\theta=0}^{\theta \max} A^2(\theta) & \sum_{\theta=0}^{\theta \max} A(\theta)B(\theta) \\ \sum_{\theta=0}^{\theta \max} A(\theta)B(\theta) & \sum_{\theta=0}^{\theta \max} B^2(\theta) \end{bmatrix}^{-1} \begin{bmatrix} \sum_{\theta=0}^{\theta \max} A(\theta)r(\theta) \\ \sum_{\theta=0}^{\theta \max} B(\theta)r(\theta) \end{bmatrix} \quad \text{from equation (19)}$$

$$\begin{bmatrix} \frac{\Delta(\lambda + 2\mu)}{(\lambda + 2\mu)} \\ \frac{\Delta\rho}{\rho} \end{bmatrix} = \begin{bmatrix} \sum_{\theta=0}^{\theta \max} C^2(\theta) & \sum_{\theta=0}^{\theta \max} C(\theta)D(\theta) \\ \sum_{\theta=0}^{\theta \max} C(\theta)D(\theta) & \sum_{\theta=0}^{\theta \max} D^2(\theta) \end{bmatrix}^{-1} \begin{bmatrix} \sum_{\theta=0}^{\theta \max} C(\theta)r(\theta) \\ \sum_{\theta=0}^{\theta \max} D(\theta)r(\theta) \end{bmatrix} \quad \text{from equation (20)}$$

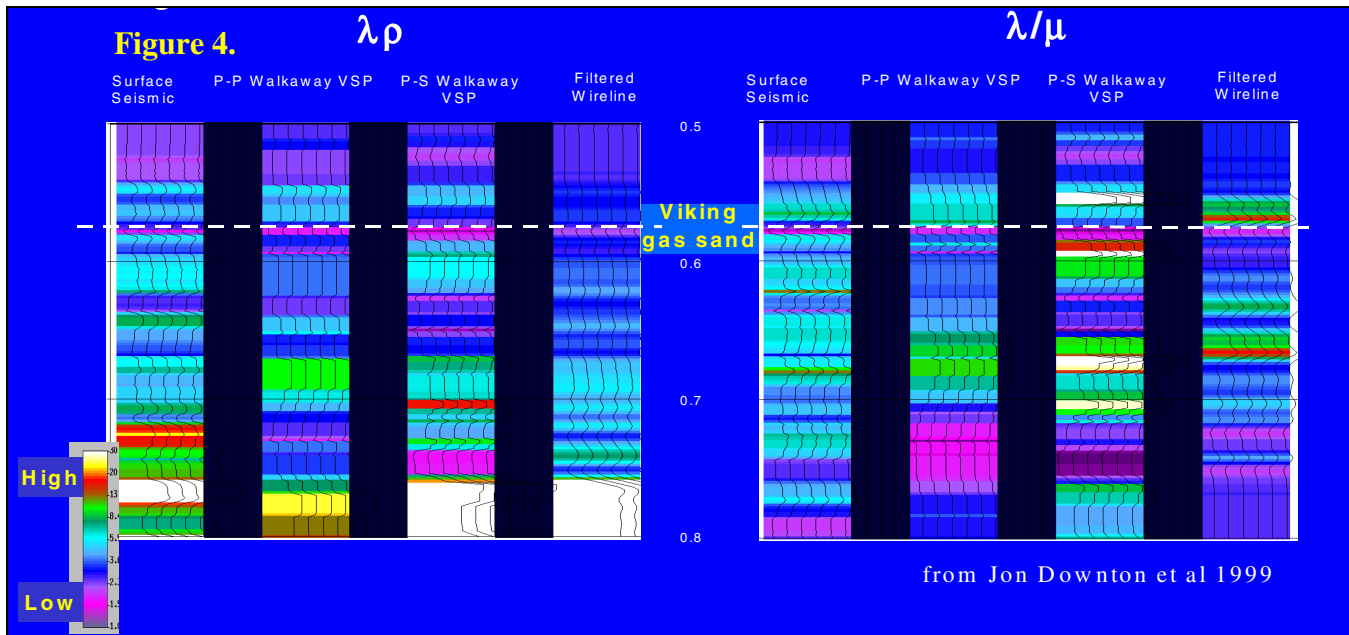
This combined PP/PS method is stable and robust with a further constraint in that the fractional P-modulus  $\Delta(\lambda+2\mu)/(\lambda+2\mu)$  term estimated from both (19) and (20) matrix equations must converge. However the method does require a nearly perfect match between the recorded

PP and PS  $r(\theta)$ 's, which may be problematic with surface data of high PP to PS bandwidth ratio, but is readily achievable with a walkaway VSP survey as shown in figure 3, where the PS data have an apparent 20Hz improvement in bandwidth (time axis compression) over PP.



**Case study seismic and walkaway VSP AVO inversion for elastic parameters.**

A walkaway VSP (figure 3) provides a real seismic data set for calibration of surface AVO, as well as the evidence of a quantifiable AVO response (Downton, Goodway & Chen 1999). This surface to borehole VSP seismic calibration has a number of advantages in that a VSP is a controlled experiment where the results are directly tied to well logs, so that it is possible to quantify the reliability of the different AVO methods described above. 3D surface seismic was also acquired and processed in a similar fashion to the VSP and an example of estimating elastic parameters from an AVO extraction on both the P-wave surface and VSP seismic data, as well as the VSP PS converted wave data is shown in figure 4. The Viking gas sand is clearly identified and remarkably well resolved at all measurement scales.



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